

Neuromorphic Computing In the European HBP Programmatic Aspects

Karlheinz Meier
Heidelberg University
NICE2017, IBM, Almaden



European Framework Funding Program Horizon 2020

Total Budget 2014- 2020 (project start dates) : 79 B€

Excellence in Science : 24 B€

ERC (individual researchers) : 13 B€

Marie-Curie (mobility) : 6.1 B€

Infrastructures : 2.2 B€

Future Emerging Technologies (FET) : 2.7 B€

FET open : approx. 1.1 B€

FET proactive : approx. 0.8B€

FET flagships : approx. 0.8B€

Graphene : approx. : 0.4 B€

Human Brain Project : approx. : 0.4 B€

NEW : Quantum Technologies : ??

Neuromorphic : approx. : 0.025 B€



*Future Emerging Technologies actions are expected to initiate radically **new lines of technology** through unexplored collaborations between advanced multidisciplinary science and cutting-edge engineering.*



*HBP Neuromorphic Computing Systems will use **brain-like principles of computing** and architectures to achieve high-energy efficiency and fault tolerance, together with **learning and cognitive capabilities** comparable to those of biological organisms.*



Funding and Contractual Structure of the HBP

Pilot Phase

12 months

Ramp-up phase

October 2013 – March 2018

Specific grant agreement SGA1

Start April 2016 – March 2018

Specific grant agreement SGA2

Start April 2018 – March 2020

Currently under preparation

.....

Funded through
Framework Program 7

Funded through
Horizon 2020

Project specific
Framework Partnersgip
agreement (FPA)

APPROVED

FET FLAGSHIPS

Interim Evaluation

*... likewise for the Human Brain Project,
even though it is still at an early stage.
Developments such as the neuromorphic
computing architectures have scope for
high economic impact ...*

The basic idea of the Human Brain Project

From **Science** to **Infrastructures** to **Science** and **Innovation**

Co-Design

Mouse

Human

Cognition

Theory

HBP
Neuroscience

HBP Platforms - Unified access through

Neuroinformatics

Brain Simulation

HPAC

Medical
Informatics

Neuromorphic

Neurorobotics

Knowledge
About the brain
Basic Science

Application in
brain technology
Innovation

What **USERS** get from the platforms



HBP Neuromorphic Computing Machines



MANY-CORE NUMERICAL MODEL SYSTEM

0.5 – 1 Million ARM processors – address-based, small packet, asynchronous communication – real-time simulation

Location : Manchester (UK)

PHYSICAL MODEL SYSTEM

Local analog computing with 4 Million neurons and 1 Billion synapses – binary, asynchronous communication – x 10 000 accelerated emulation

Location : Heidelberg (Germany)





HBP neuromorphic computing - The 1st generation



Concepts developed around 2005

... state-of-the-art ... Now doing the next step in HBP

SGA1: Proof of concept - SGA2: Operational 2nd generation systems

Next generation of NM computing in the HBP

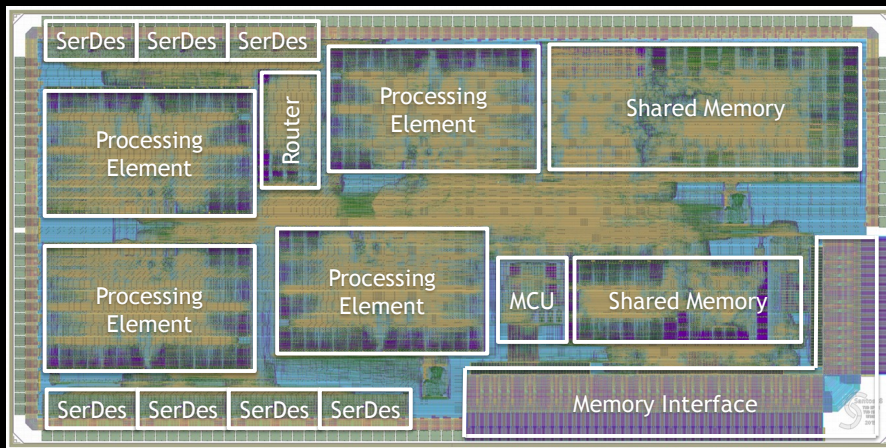
SpiNNaker-2

4-core Quad Processing Element

25 GIPS/W on a single die

Floating point precision

True random numbers



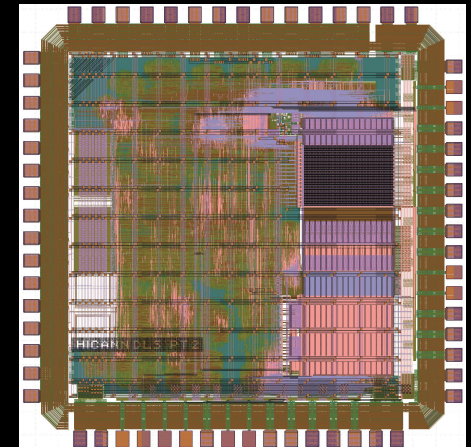
BrainScales-2

Flexible local learning

On-the-fly network reconfiguration

Structured neurons

Dendritic computation



Today : Working prototypes

2020 : Operational systems

Overall goal : **Learning cognitive machines**

OPERATION – MACHINES – PRINCIPLES - APPLICATIONS

9.1 Software services and platform op.	Andrew Davison	CNRS
9.2 Next generation BrainScaleS machine	Johannes Schemmel	Heidelberg
9.3 Next generation SpiNNaker machine	Steve Furber	Manchester
9.4 Computational principles	Wolfgang Maass	Graz
9.5 Applications and Benchmarks	Michael Schmuker	Hertfordshire
9.6 Management and training	Björn Kindler	Heidelberg
Subproject leader	Karlheinz Meier	
Subproject co-leader	Steve Furber	

Goal : Learning Cognitive Machines

HBP Neuromorphic Computing Platform Guidebook

next: [Getting started](#)

The HBP Neuromorphic Computing Platform

Living document version:

6ae0000e Wed, 22 Feb 2017 17:03:48 GMT

The Neuromorphic Computing Platform allows neuroscientists and engineers to perform experiments with configurable neuromorphic computing systems. The platform provides two complementary, large-scale neuromorphic systems built in custom hardware at locations in Heidelberg, Germany (the "BrainScaleS" system, also known as the "physical model" or PM system) and Manchester, United Kingdom (the "SpiNNaker" system, also known as the "many core" or MC system). Both systems enable energy-efficient, large-scale neuronal network simulations with simplified spiking neuron models. The BrainScaleS system is based on physical (analogue) emulations of neuron models and offers highly accelerated operation (10^4 x real time). The SpiNNaker system is based on a digital many-core architecture and provides real-time operation.

- [Getting started](#)
 - [Request a compute time allocation](#)
 - [Run a simulation](#)
 - [Copy data to longer-term storage](#)
- [Building models](#)
 - [The PyNN model description API](#)
 - [A simple example](#)
 - [Using different backends](#)
 - ["Physical model" \(BrainScaleS\) system](#)
 - ["Many core" \(SpiNNaker\) system](#)
- [Running simulations](#)
 - [Format of a job](#)



Next topic

[Getting started](#)

This Page

[Show Source](#)

Quick search

Enter search terms or a module, class or function name.

Presence of the HBP at NICE 2017

MON	K. Meier	The BrainScaleS physical model machine – From commissioning to real world problem solving
MON	E. Müller	DEMO Neuromorphic Hardware In The Loop: Training a Deep Spiking Network on the BrainScaleS Wafer-Scale System
TUE	S. Furber	SpiNNaker: Large-scale Real-time Neural Simulation
TUE	W. Maass	How Can Networks of Spiking Neurons Wire Themselves Up For a Specific Computational Task?
WED	J. Schemmel	Training and Plasticity Concepts of the BrainScaleS Neuromorphic Systems