



Inferring Inference

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part of the MICrONS project with Tolias,
Bethge, Patel, Zemel, Urtasun, Xu, Siapas,
Paninski, Baraniuk, Reid, Seung

NICE workshop 2017



World



Brain



Hypothesis:

The brain

approximates probabilistic inference
over a probabilistic graphical model
using a message-passing algorithm
implicit in population dynamics

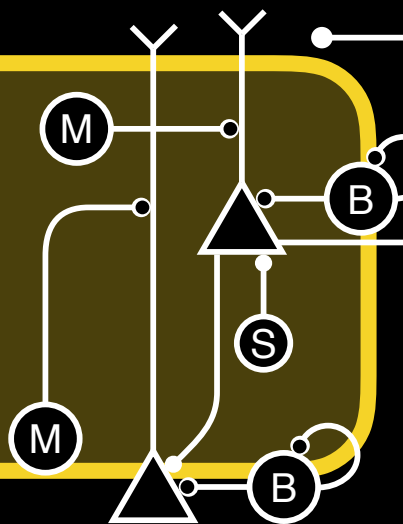
What algorithms can we learn from the brain?

Architectures?

cortex, hippocampus, cerebellum, basal ganglia, ...

Transformations?

nonlinear dynamics from population responses



Learning rules?

short and long-term plasticity

Principles:

Probabilistic

Nonlinear

Distributed

Details:

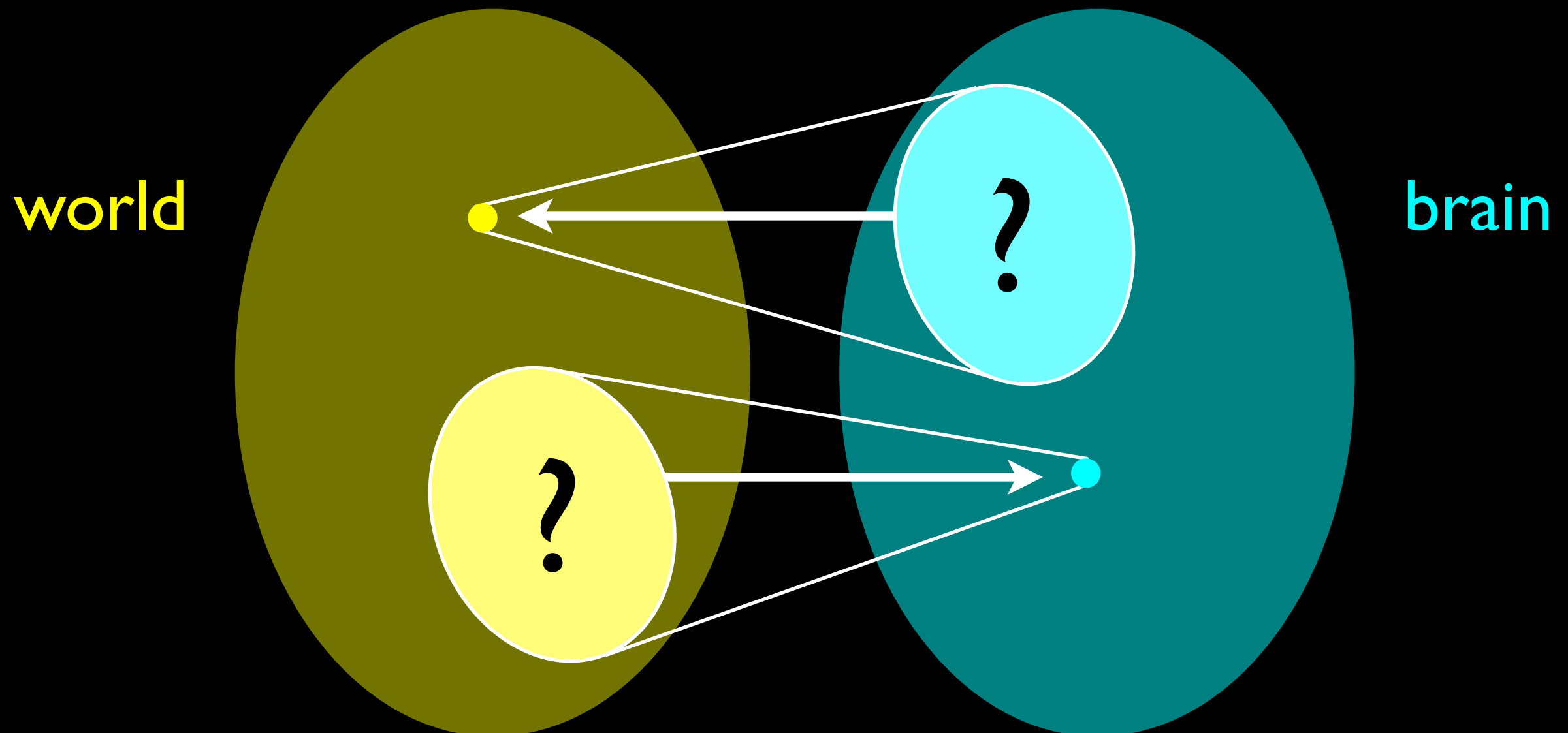
Graphical models

Message-passing inference

Multiplexed across neurons

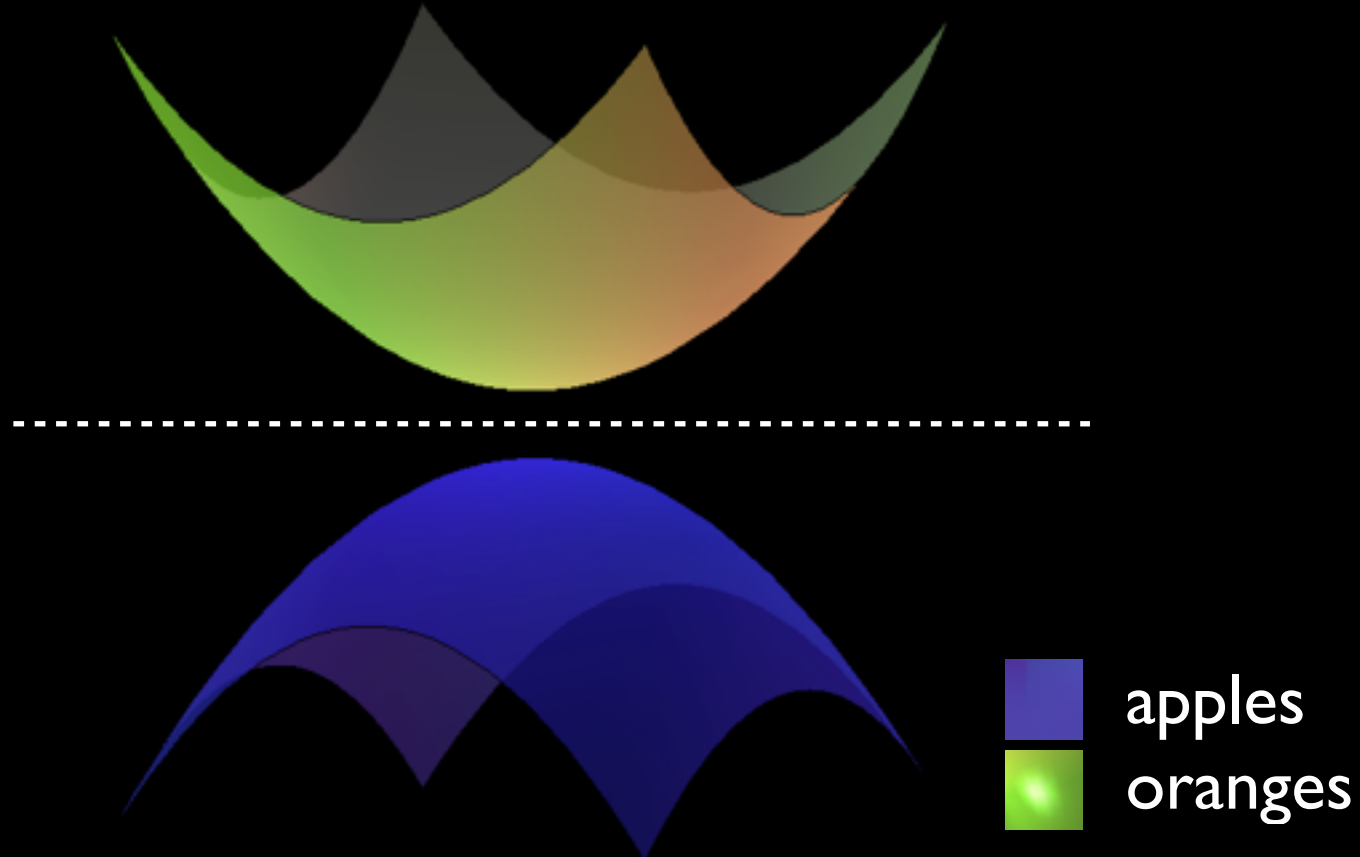
Events in the world can cause many **neural responses**.
Neural responses can be caused by many **events**.

So neural computation is inevitably **statistical**.
This provides us with mathematical predictions.

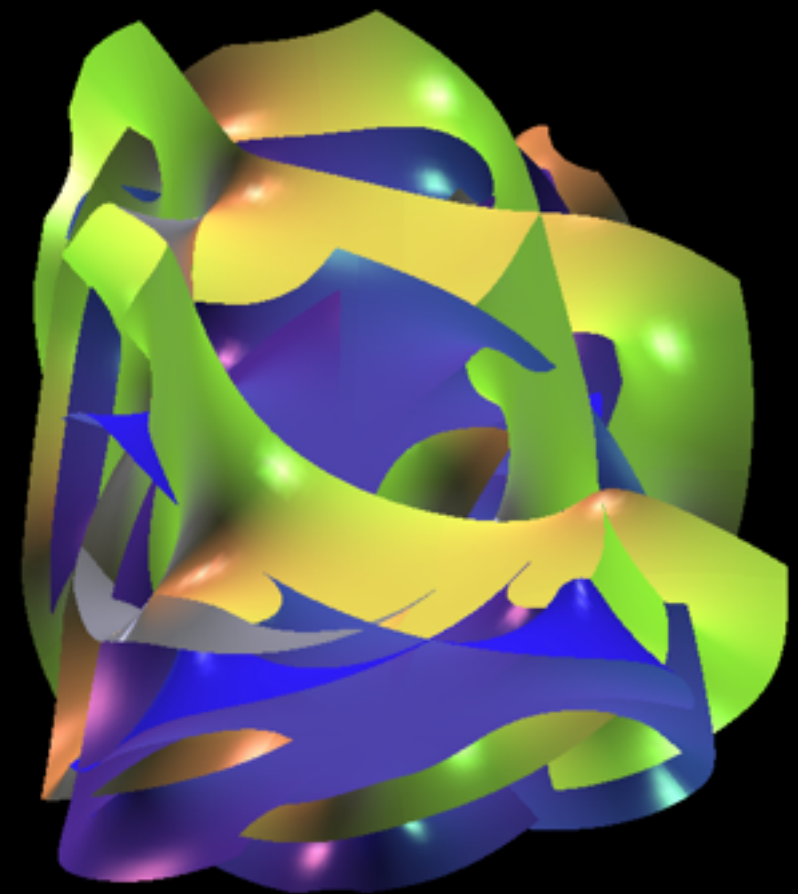


Why does it matter whether processing is linear or nonlinear?

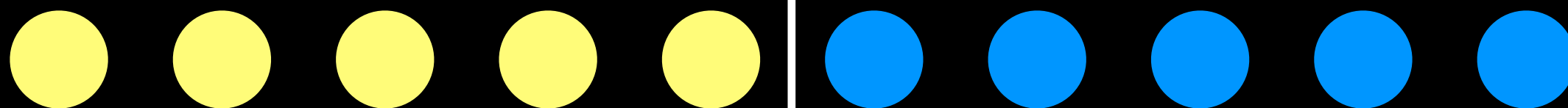
If all computation were linear we wouldn't need a brain.

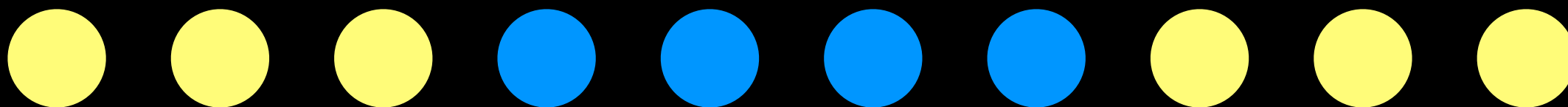


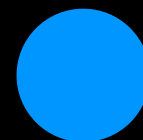
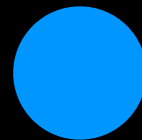
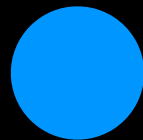
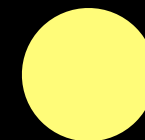
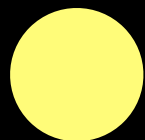
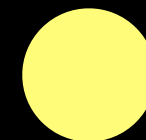
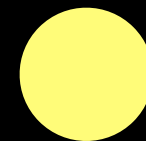
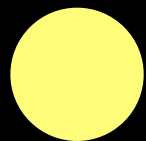
linearly separable

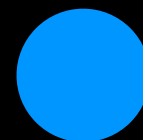
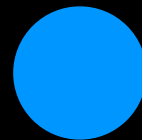
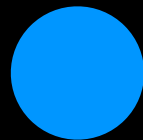
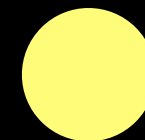
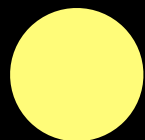
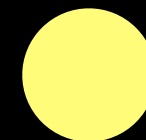
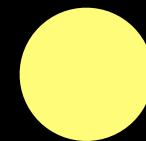
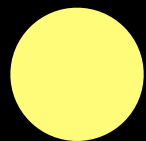


nonlinearly separable





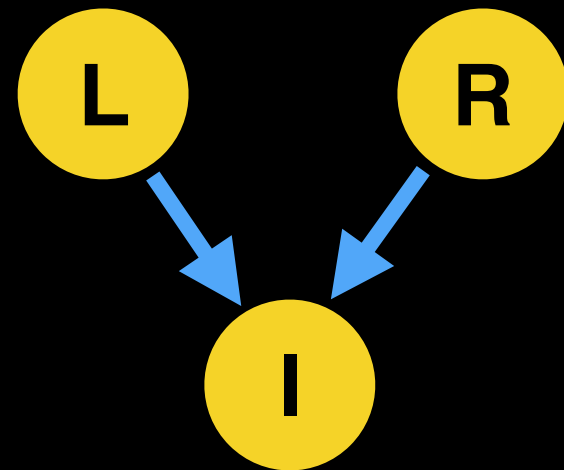




Two sources of nonlinearities

Relationships between latent variables

$$\text{Image} = \text{Light} \times \text{Reflectance}$$



Relationships between uncertainties

posteriors generally have nonlinear dependencies even for the simplest variables

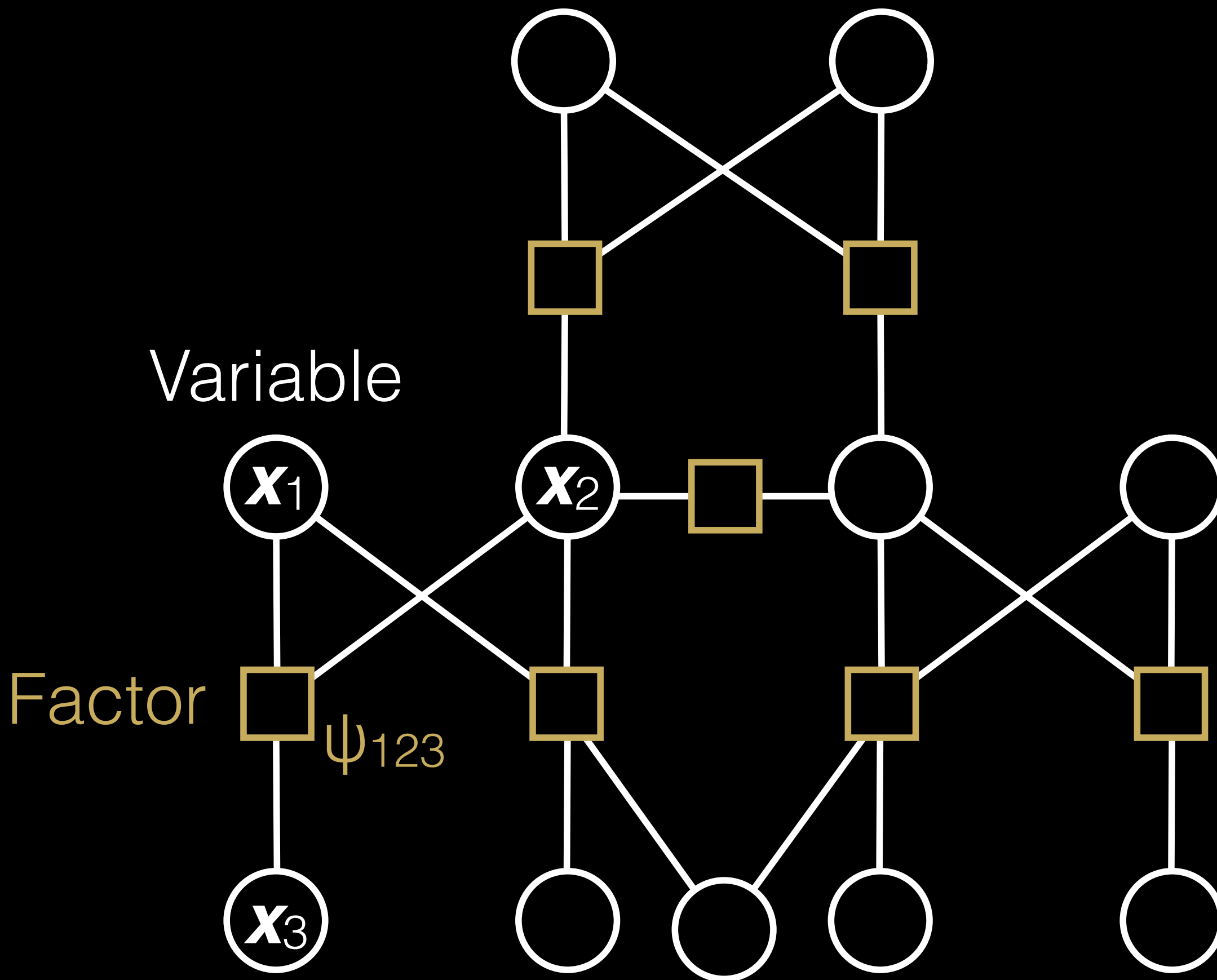
Product rule: $p(x,y) = p(x) \cdot p(y)$

Sum rule: $L(x) = \log \sum_y \exp L(x,y)$

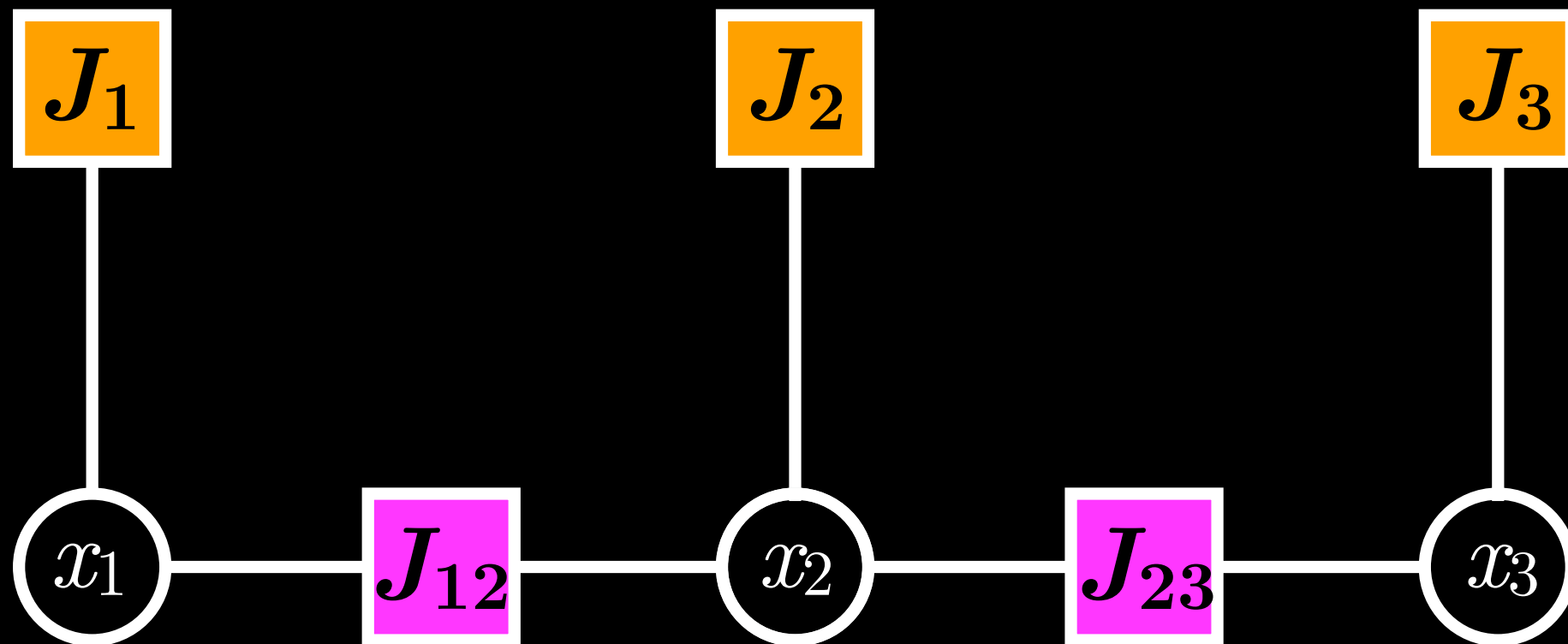
Probabilistic Graphical Models:

Simplify joint distribution $p(\mathbf{x}|\mathbf{r})$ by specifying how variables interact

$$p(\mathbf{x}|\mathbf{r}) \propto \prod_{\alpha} \psi_{\alpha}(\mathbf{x}_{\alpha})$$



Example: Pairwise Markov Random Field



$$p(\boldsymbol{x}) = \frac{1}{Z} \prod_{s \in V} e^{\boldsymbol{J}_s(\boldsymbol{x}_s)} \prod_{(s,t) \in E} e^{\boldsymbol{J}_{st}(\boldsymbol{x}_{st})}$$

Approximate inference by *message-passing*:

- Localize information so it is actionable
- Summarize statistics relevant for targets
- Send that information *along graph*
- Iteratively update factors with new information

$$\theta_{i,t+1} = f(\theta_{it}, \{\theta_{jt}\}_{j \in N_i} \mid G, J)$$

general equation

posterior parameters

posterior for neighbors

interactions

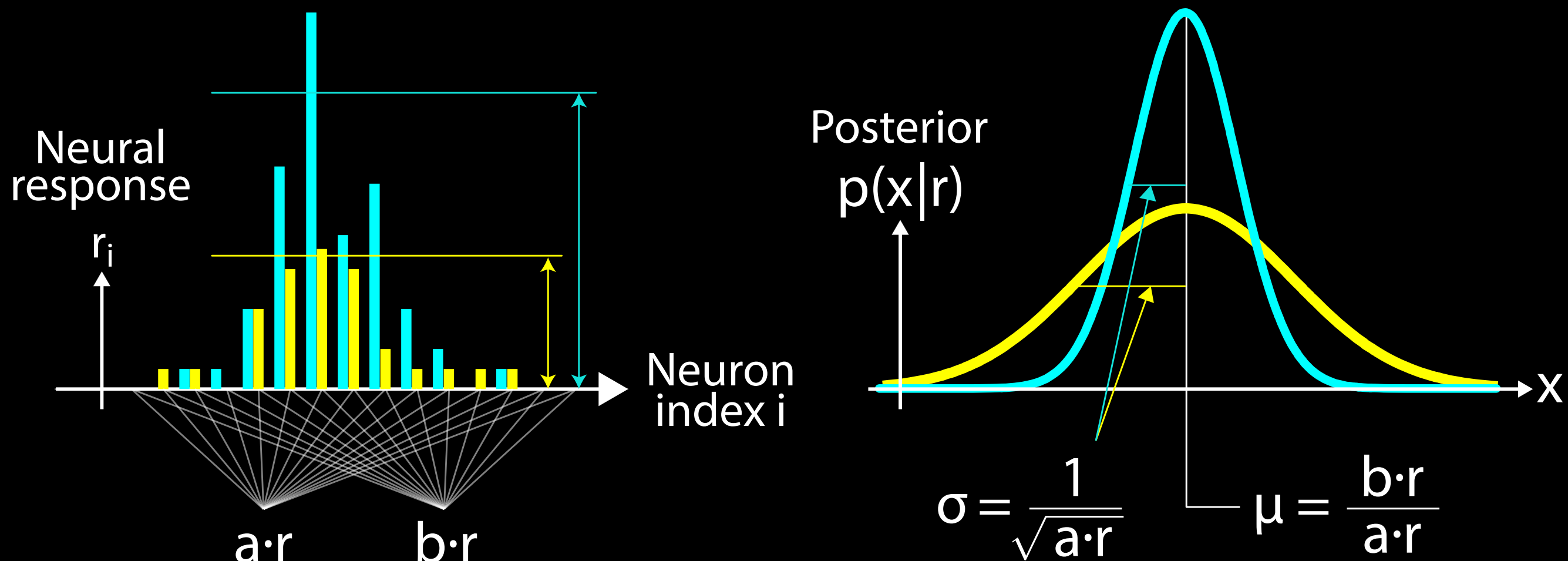
message-passing parameters

Example message-passing algorithms

- Mean-field (assumes variables are independent)
- Belief propagation (assumes tree graph)
- Expectation propagation (updates parametric posterior)
- ...
- Brain's clever tricks?

Spatial representation of uncertainty

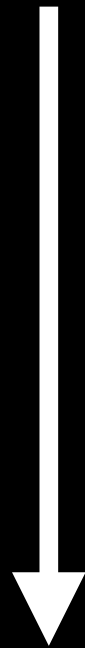
(e.g. Probabilistic Population Codes, PPCs)



Pattern of activity represents probability.
More spikes generally means more certainty

Message-passing updates

$$\theta_{i,t+1} = f(\theta_{it}, \{\theta_{jt}\}_{j \in N_i} | G, J)$$

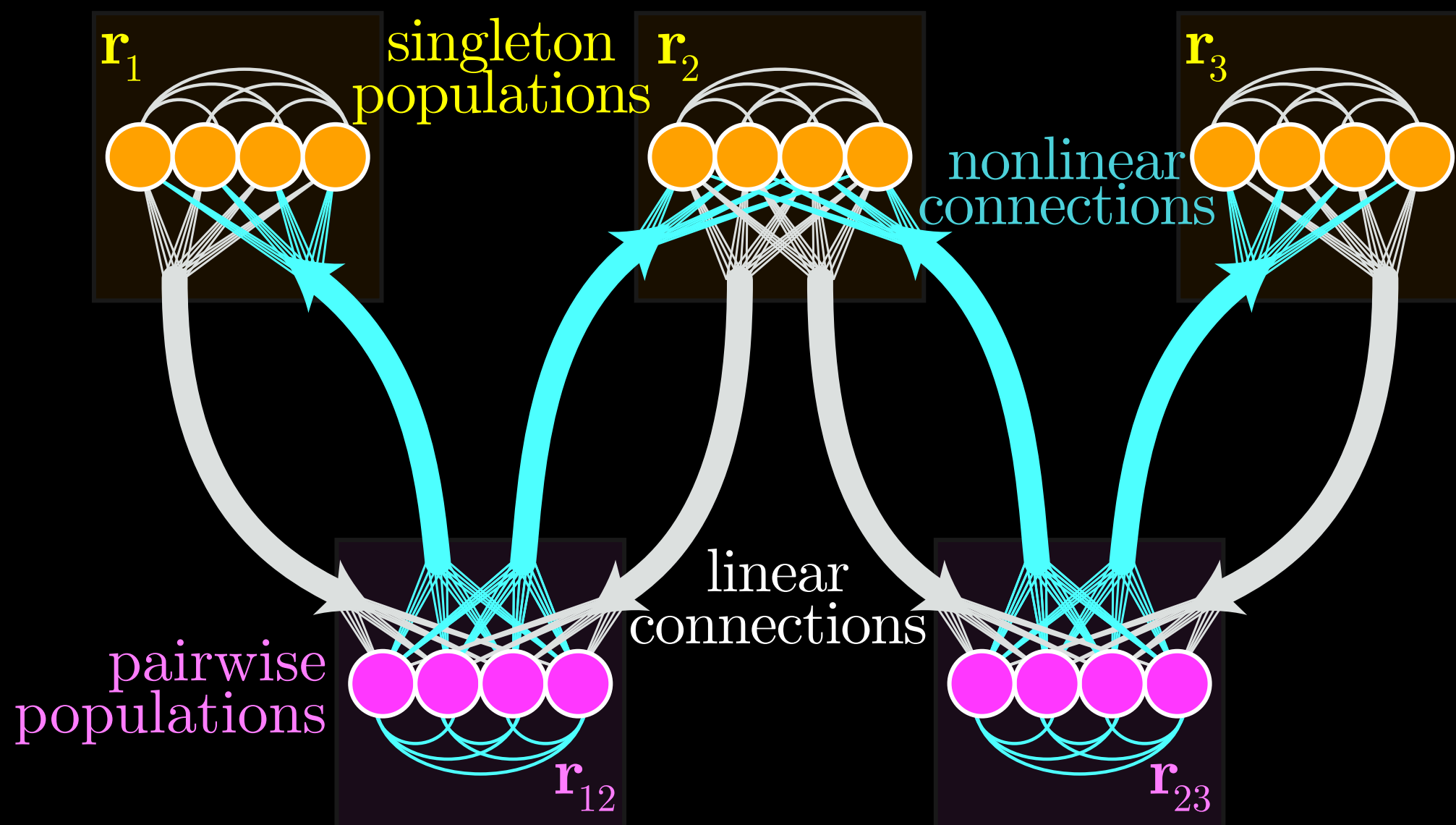
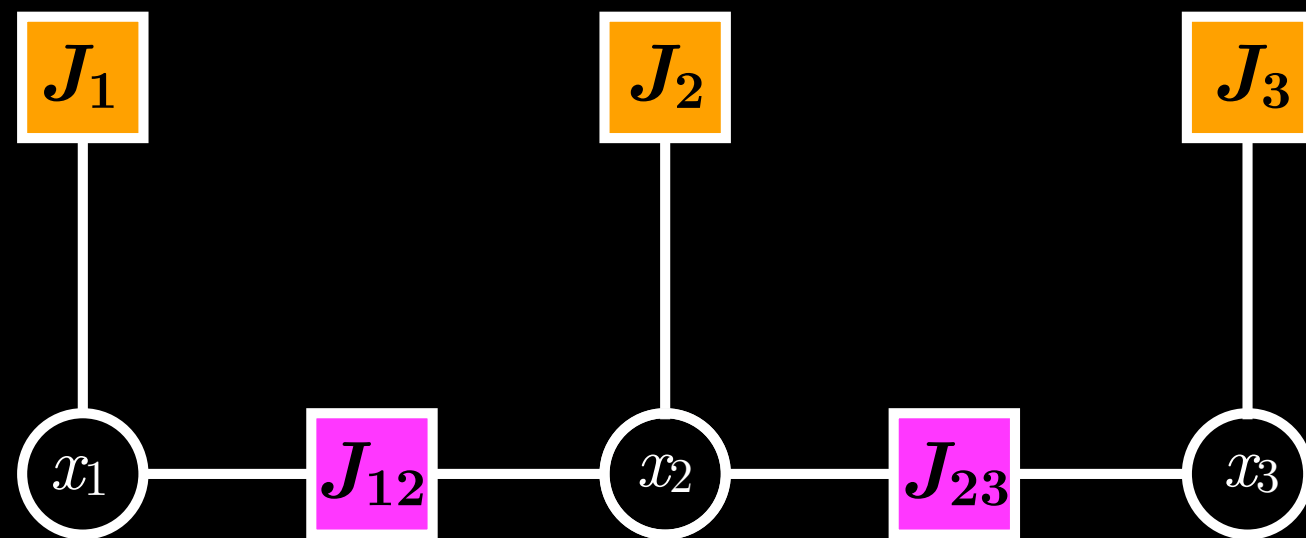


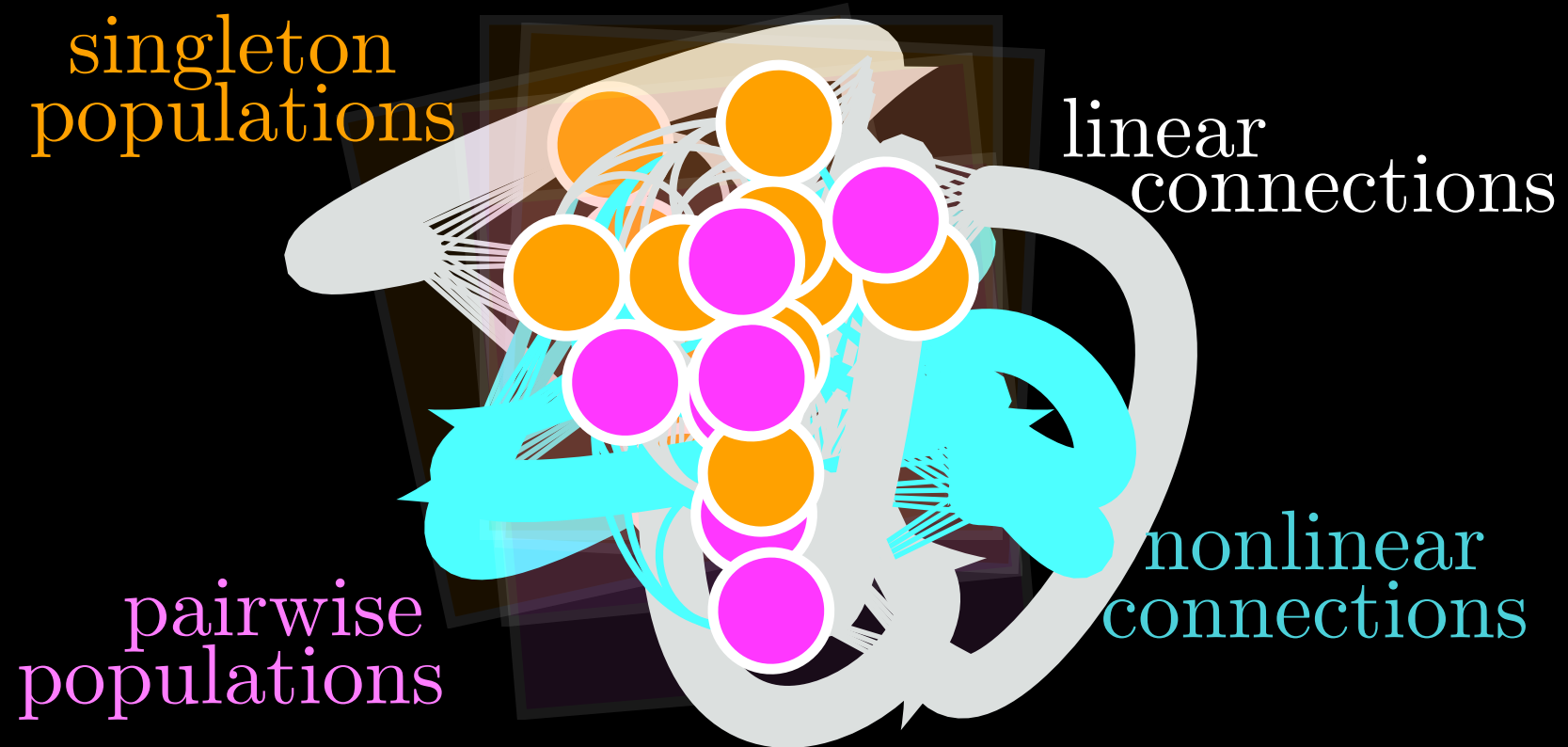
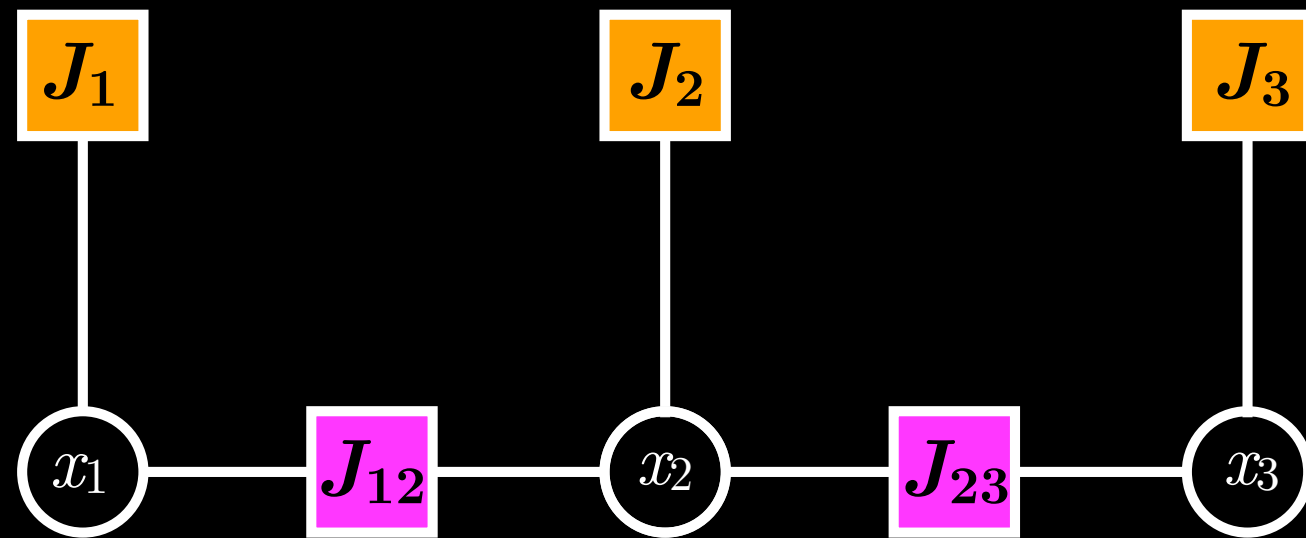
$$r = U\Theta + \eta$$

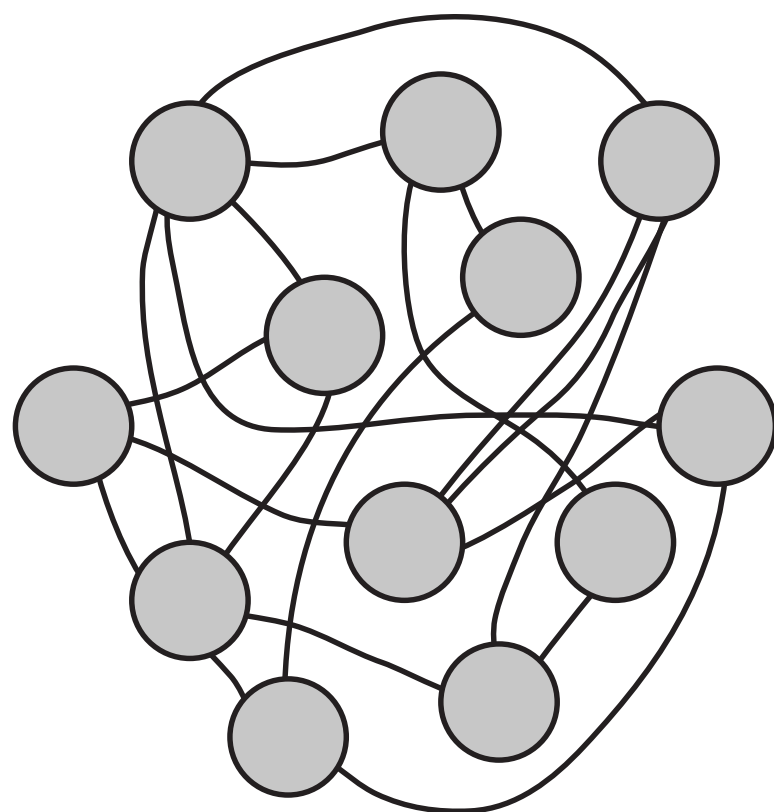
embedding

$$\dot{r} = F(r_t)$$

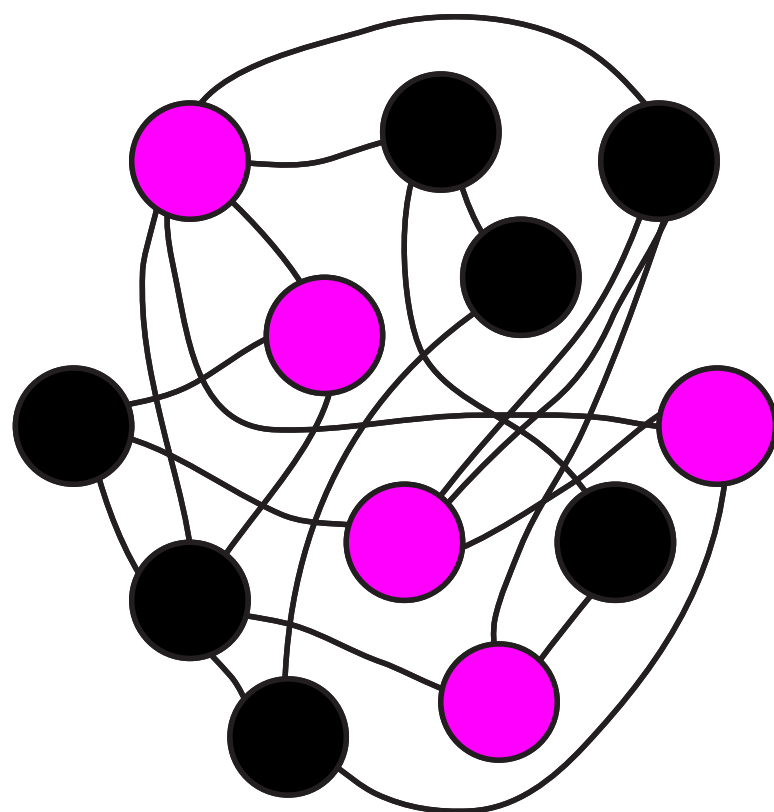
Neural dynamics



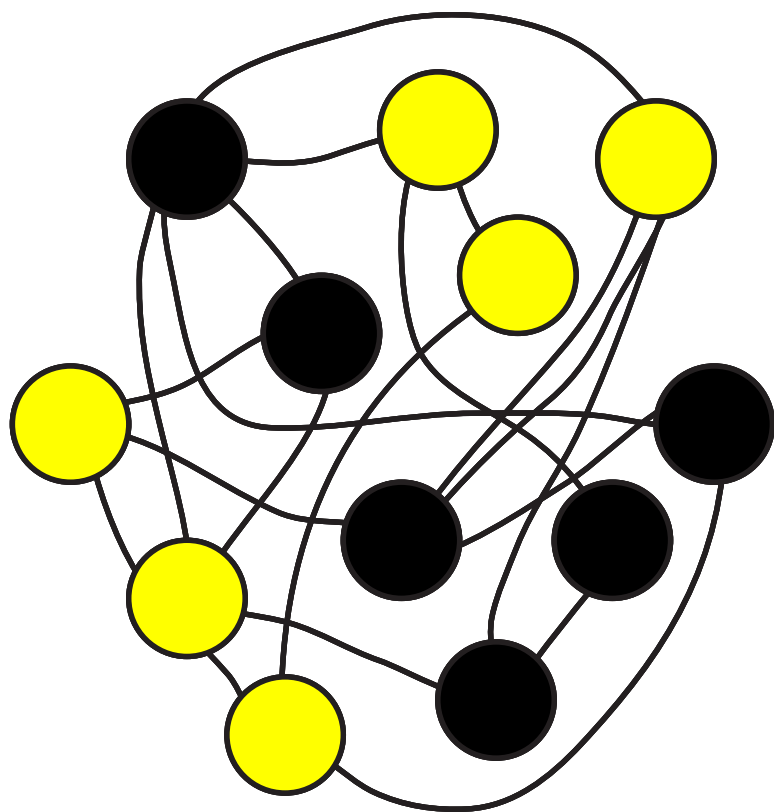




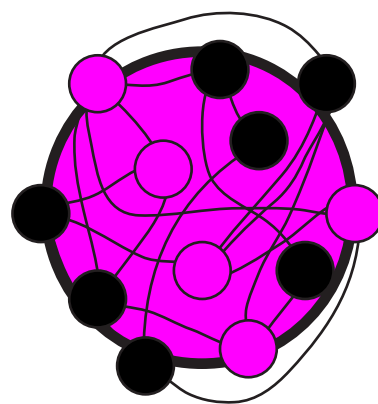
Neural
activity



Neural
activity

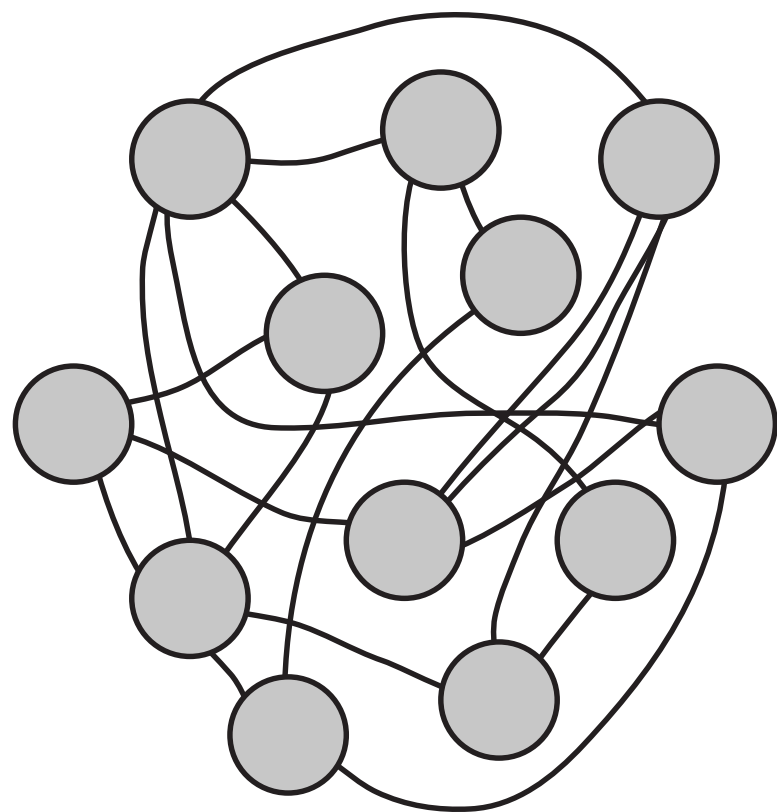


Neural
activity

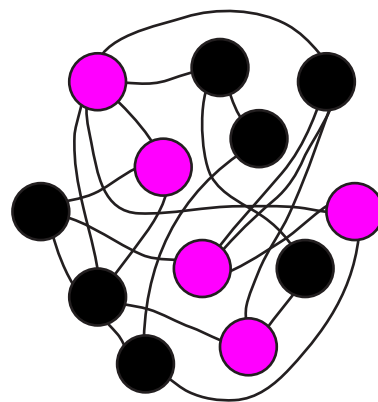


Neural
encoding

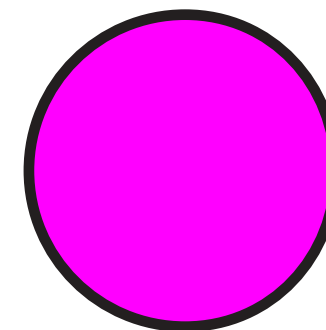
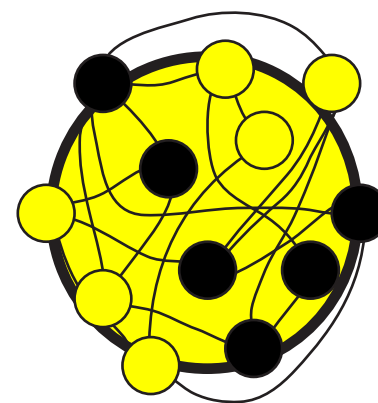
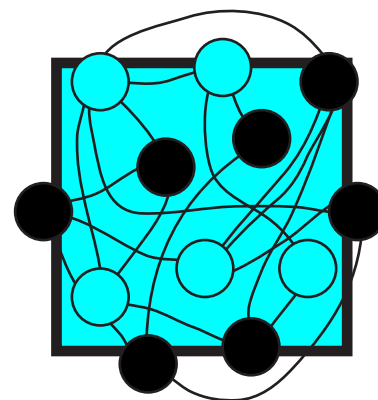
Information
encoded



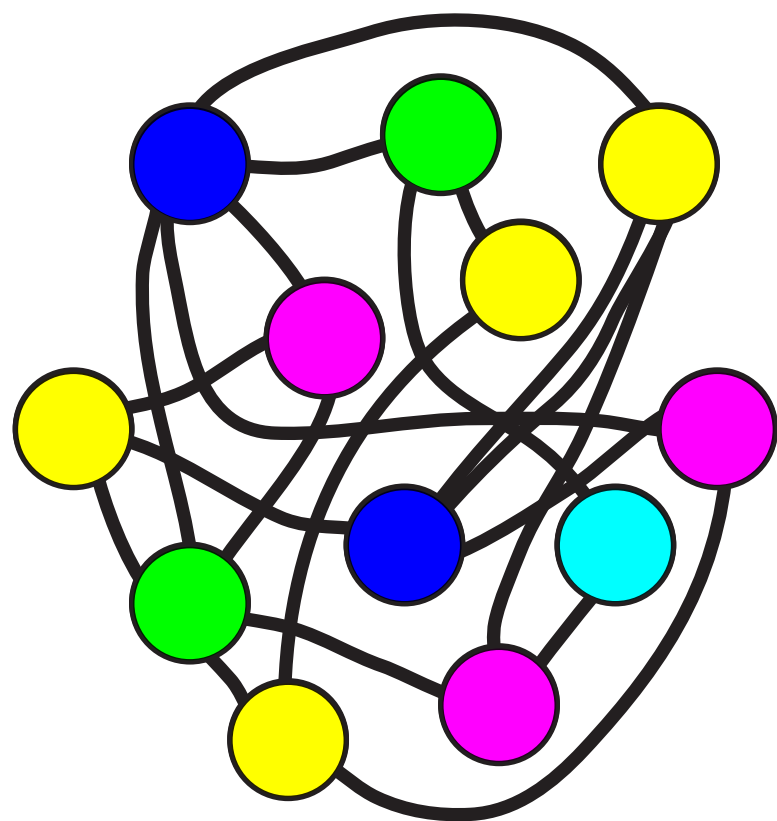
Neural
activity



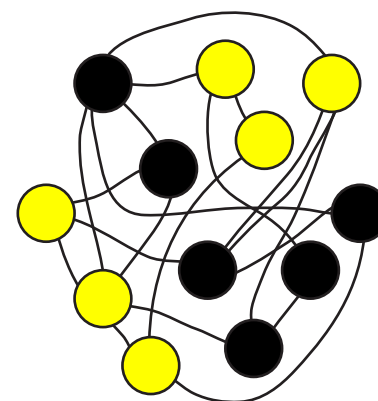
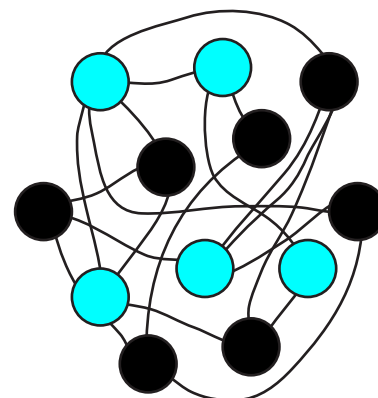
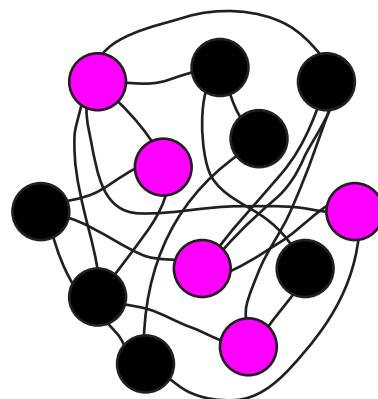
Neural
encoding



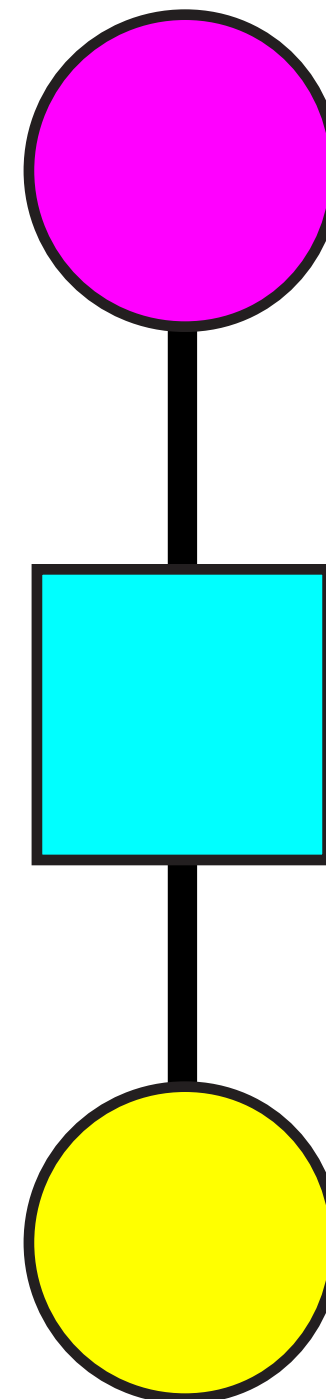
Information
encoded



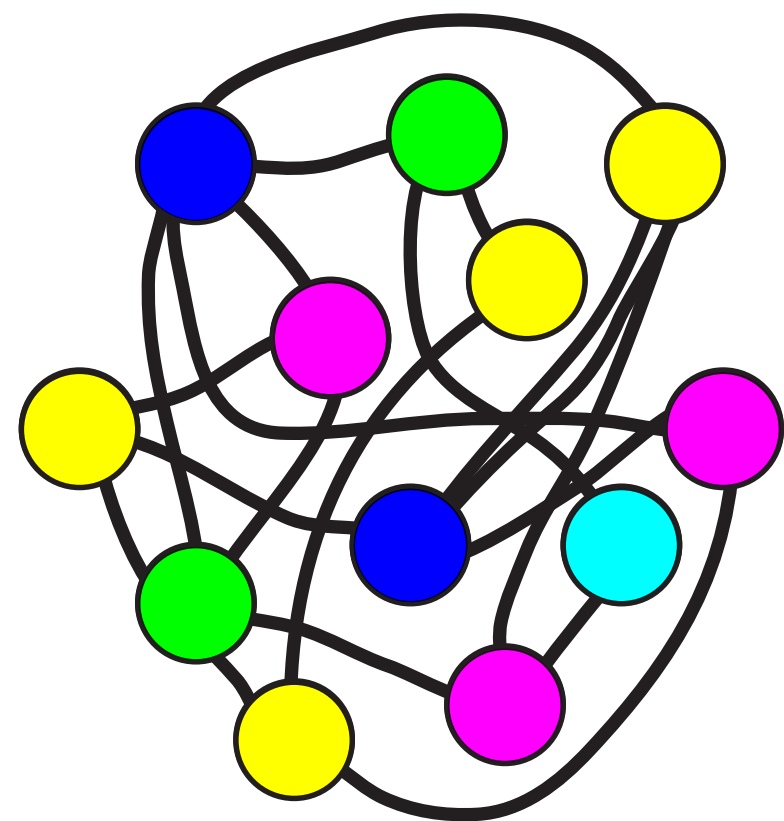
Neural
interactions



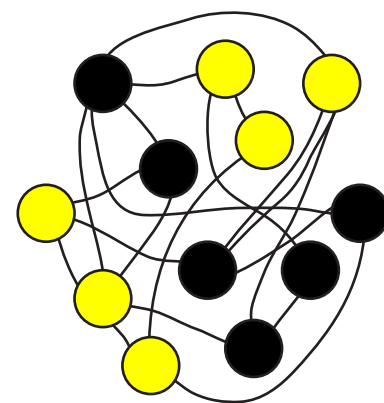
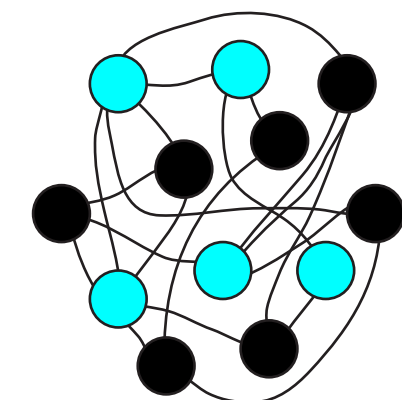
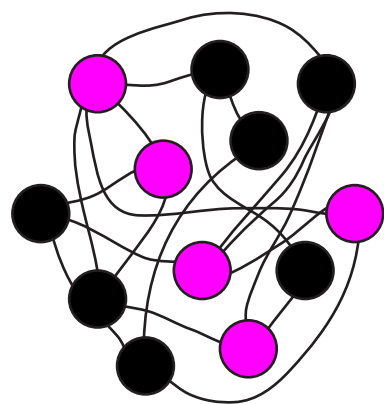
Neural
encoding



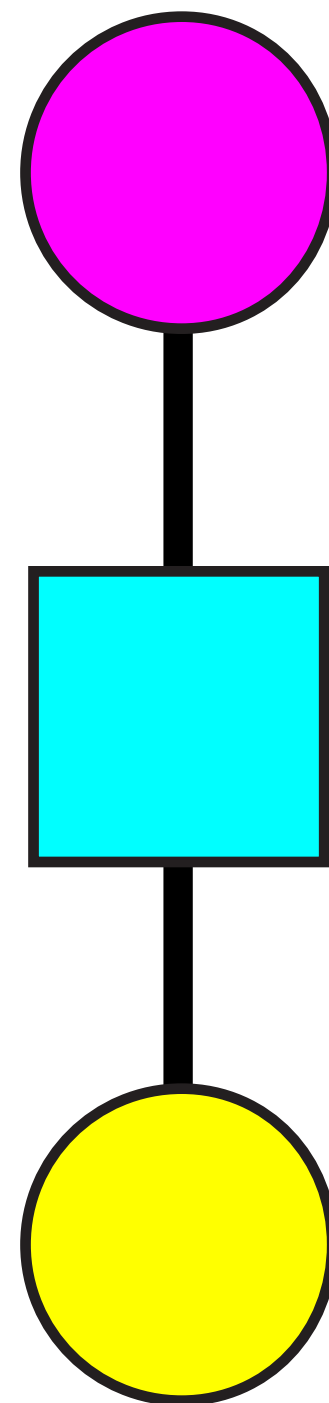
Information
interactions



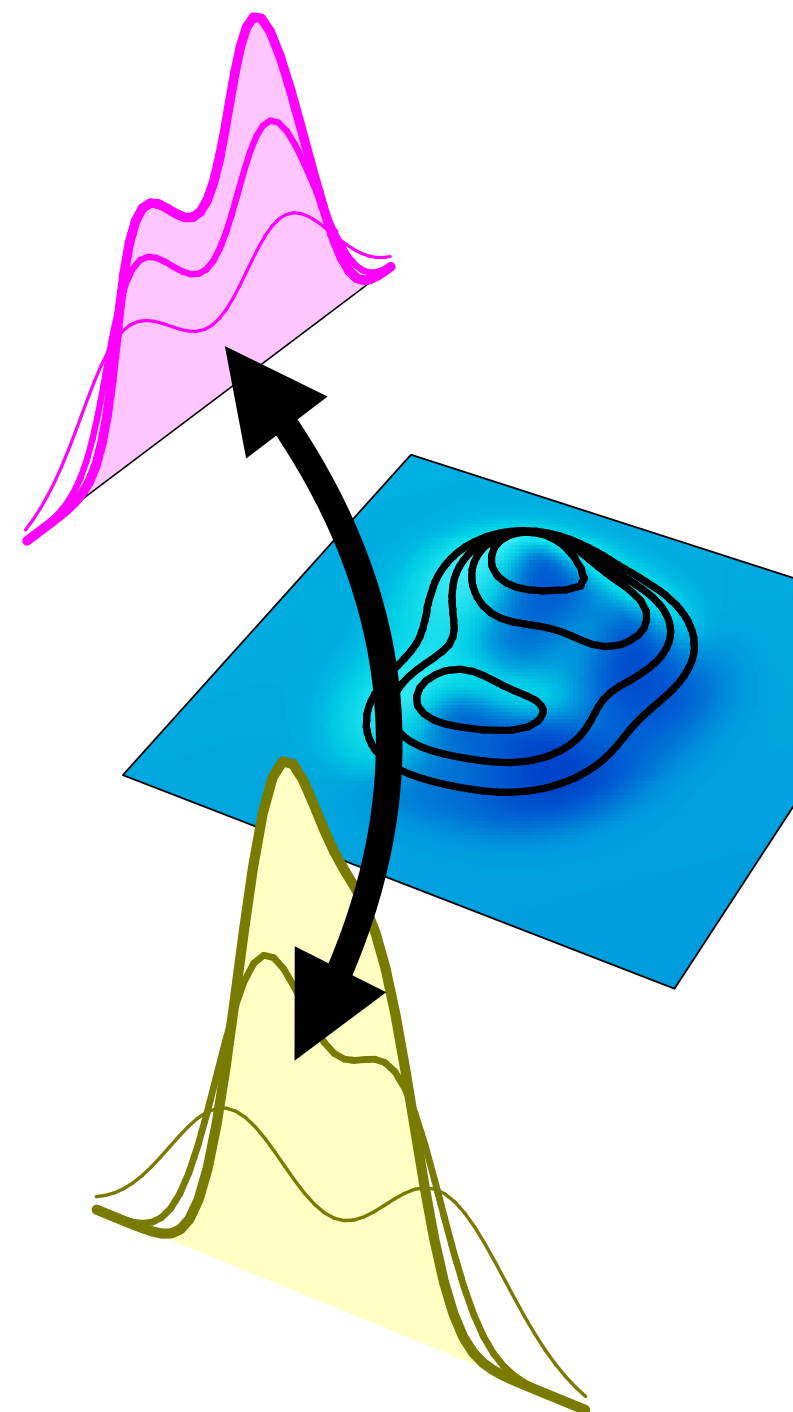
Neural
interactions



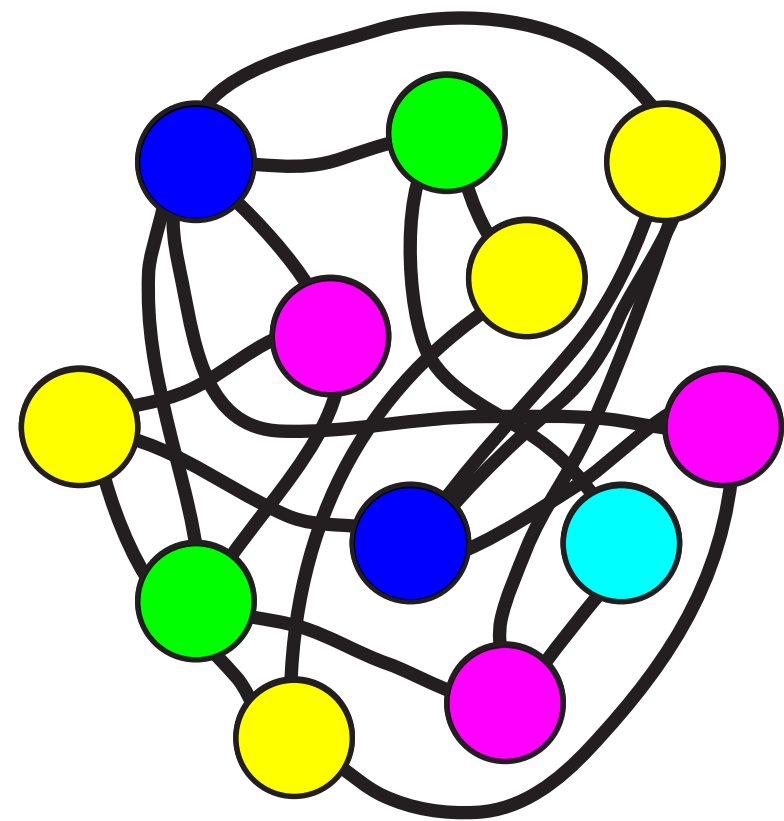
Neural
encoding



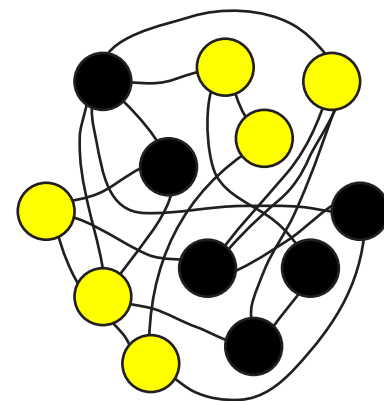
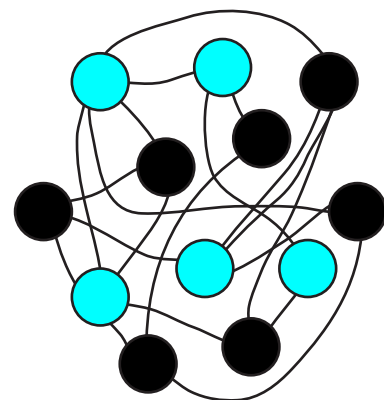
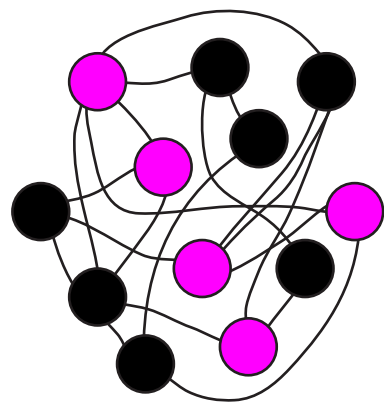
Information
interactions



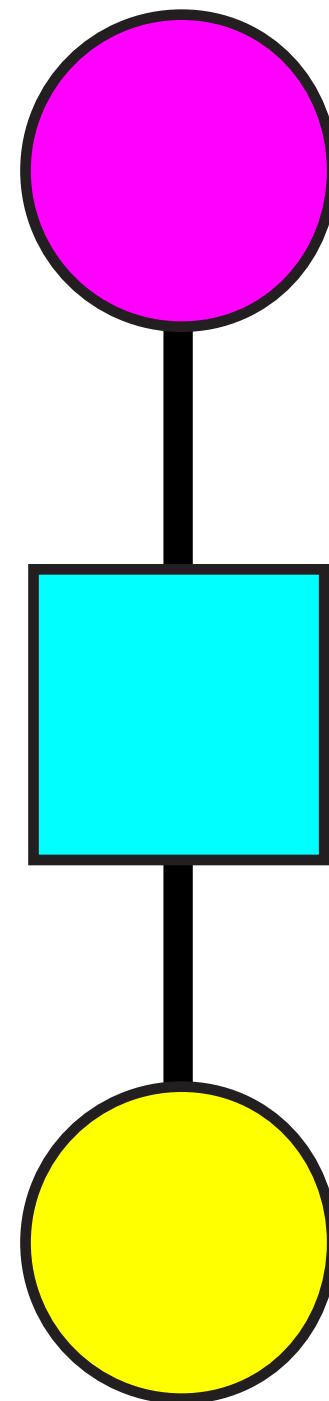
Probability
distributions



Neural
interactions

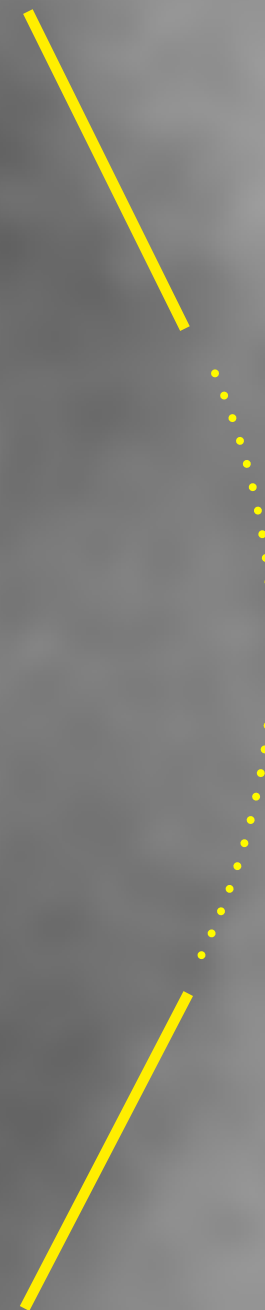


Neural
encoding

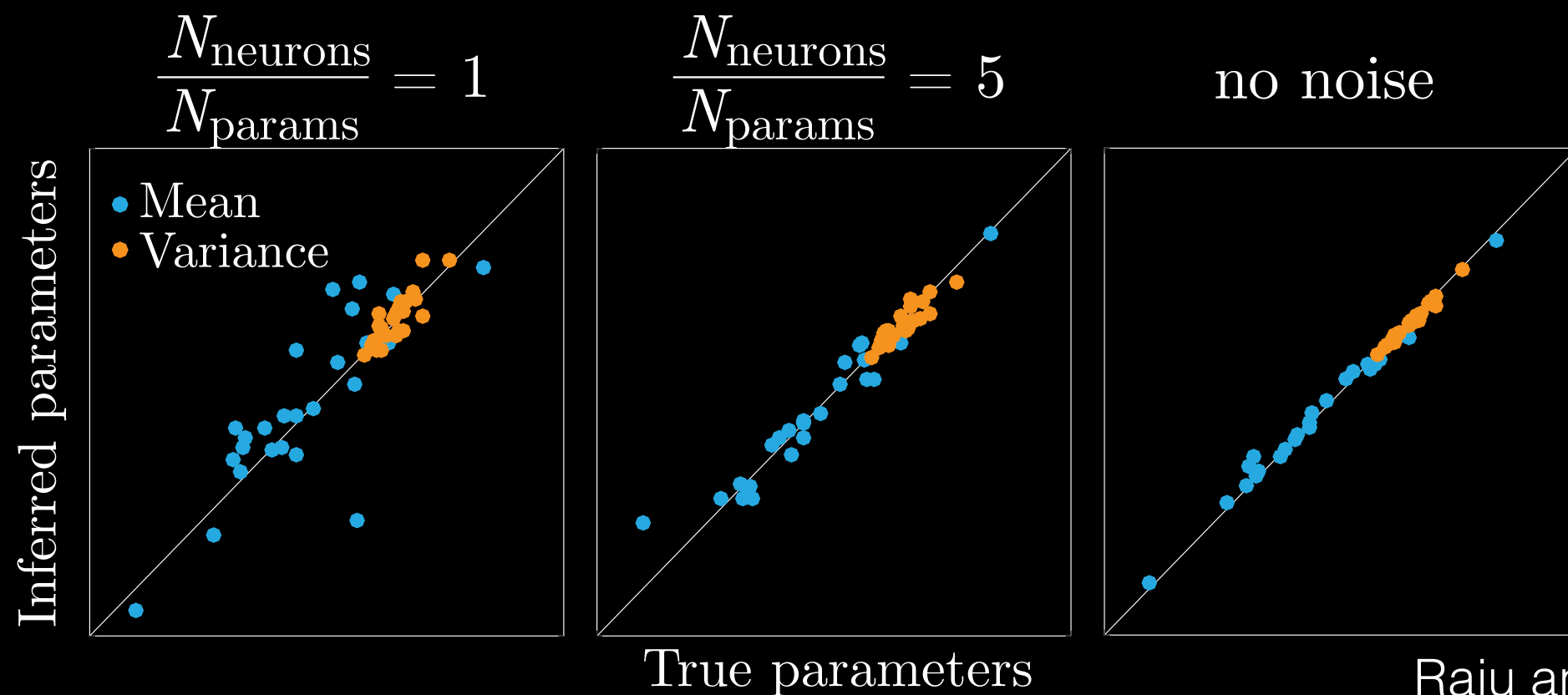
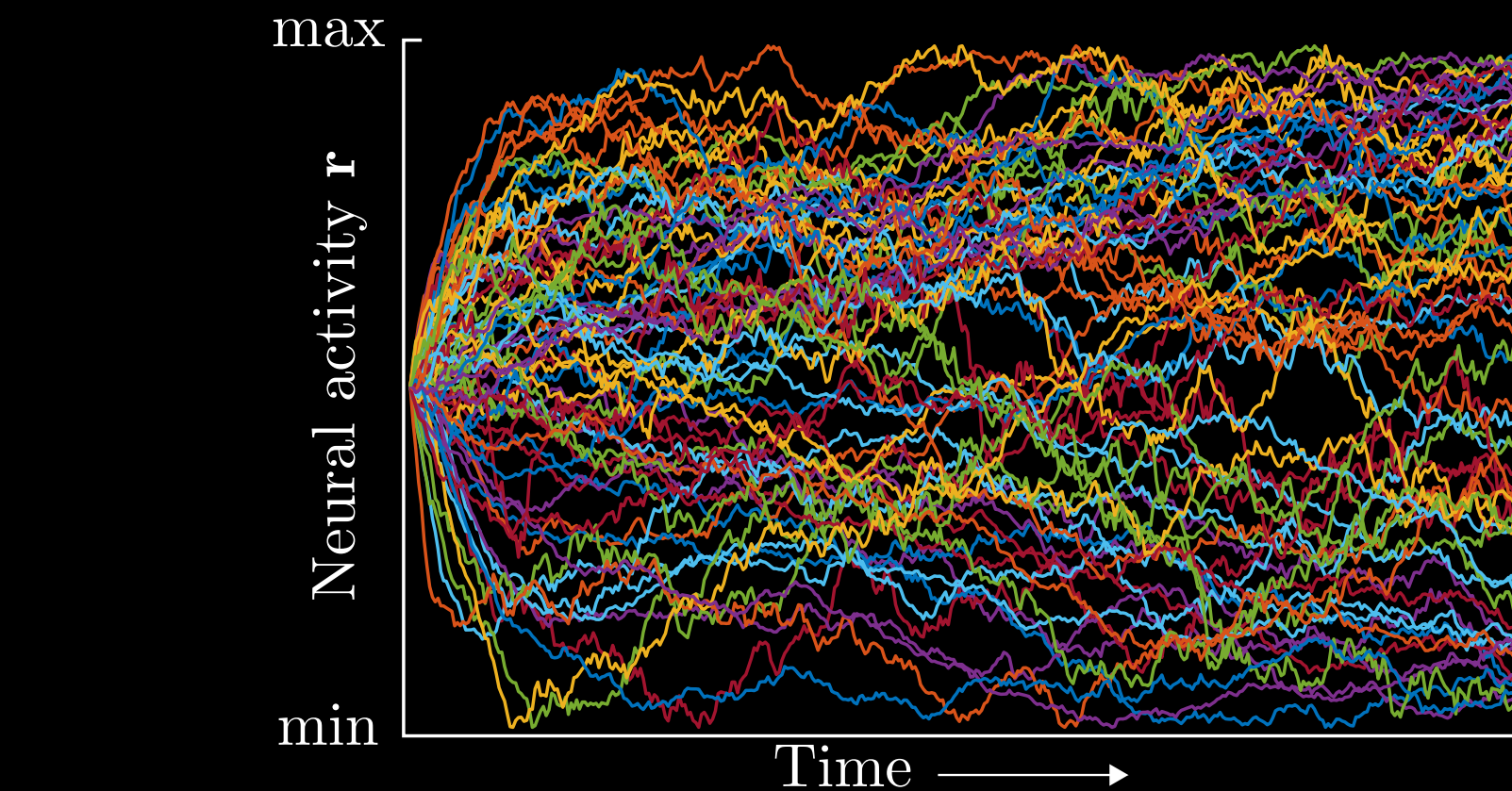


Information
interactions

Example:
orientation



Network activity can implicitly perform inference



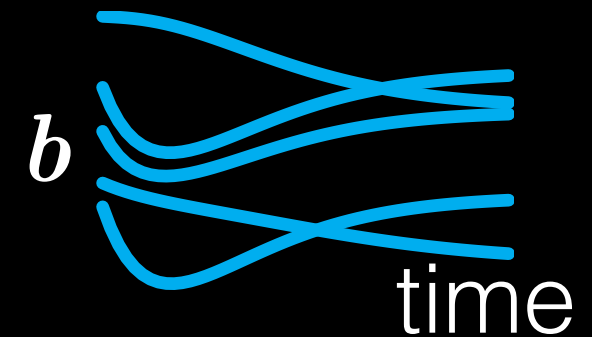
Simulated brain

$$\dot{b}_{it} = -b_{it} + \sigma \left(\sum_j W [J_{ij}, b_{it}, b_{jt}] b_{jt} + h_{it} \right)$$

$$W [J_{ij}, b_i, b_j] = 2J_{ij} + 4J_{ij}^2(1 - 2b_i)(1 - b_j)$$

$$\mathbf{r}_{t+1} = \sigma (A\mathbf{r}_t + B\mathbf{h}_t - \theta)$$

Infer



Encode



Inferring inference

$$\hat{\mathbf{b}} = V\mathbf{r} + c$$

$$\hat{W}[J_{ij}, b_i, b_j] = \sum_{\alpha\beta\gamma} \underbrace{G_{\alpha\beta\gamma}}_{\text{Message-passing parameters}} \underbrace{J_{ij}^{\alpha}}_{\text{Interactions}} b_i^{\beta} b_j^{\gamma}$$

Message-passing
parameters

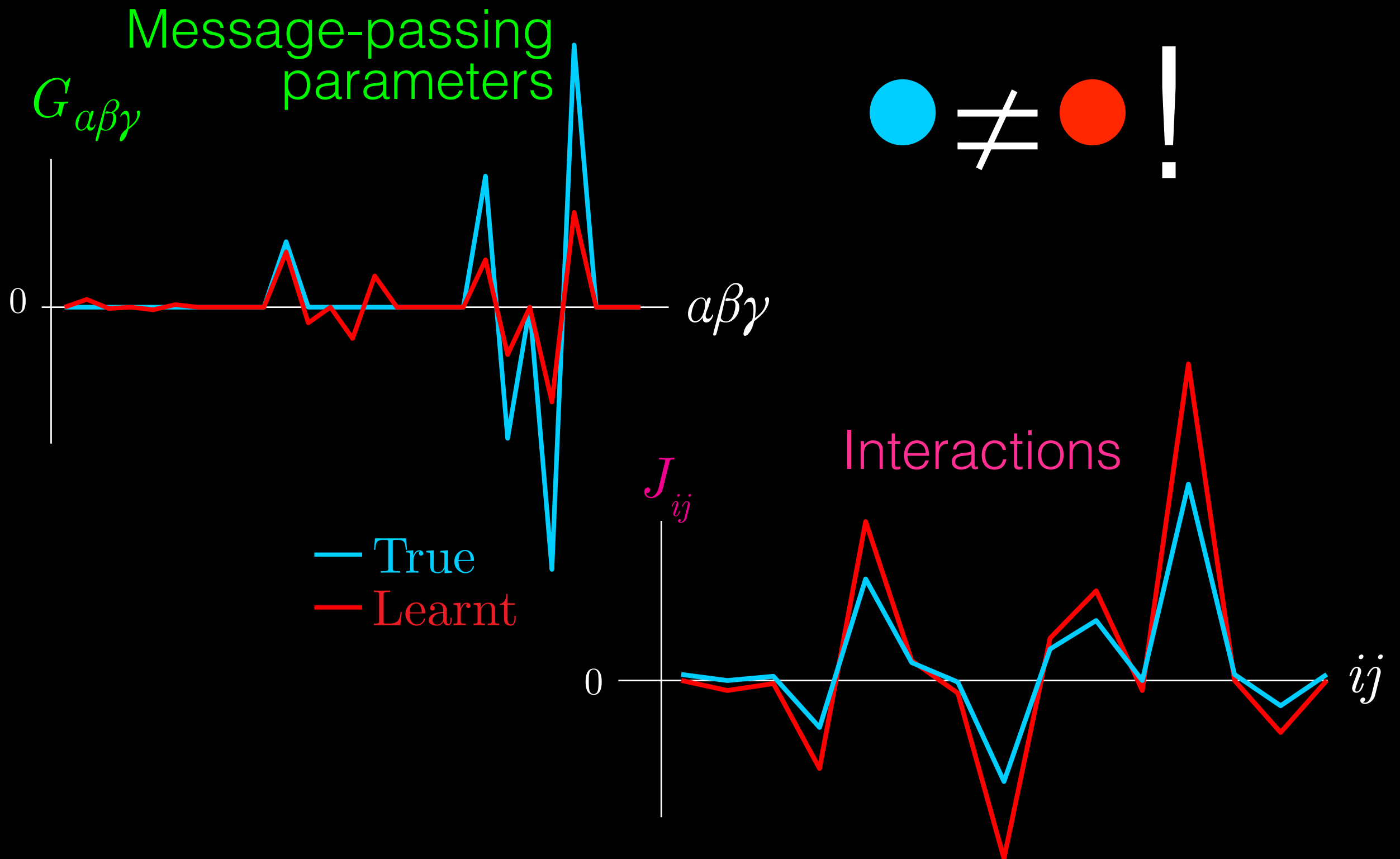
Interactions

Decode

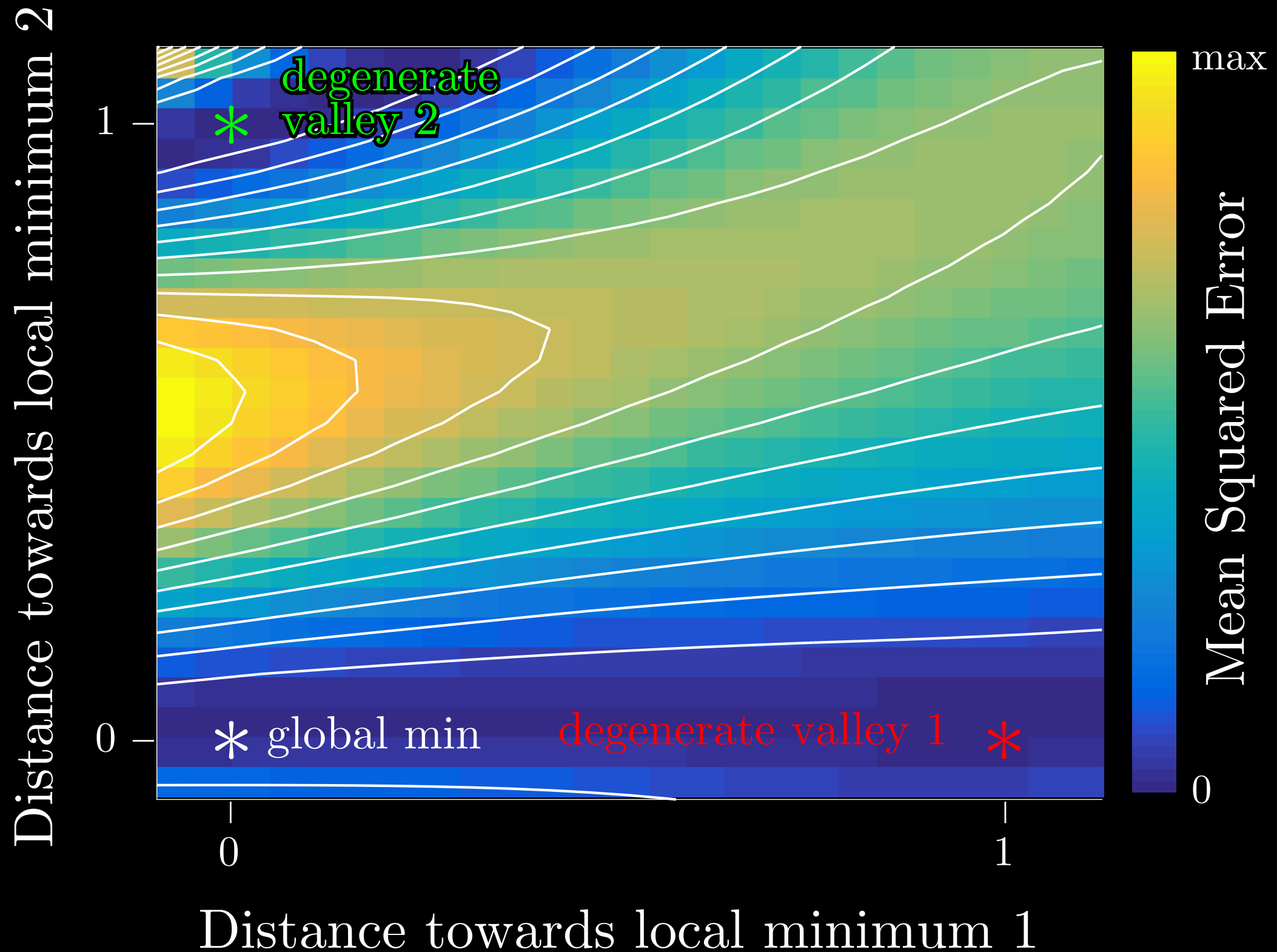
Fit*

*within
family

Recovery results for simulated brain



Analysis reveals degenerate family of *equivalent* algorithms



From *simulated* neural data we have recovered:

how variables are encoded

Representation

which variables interact

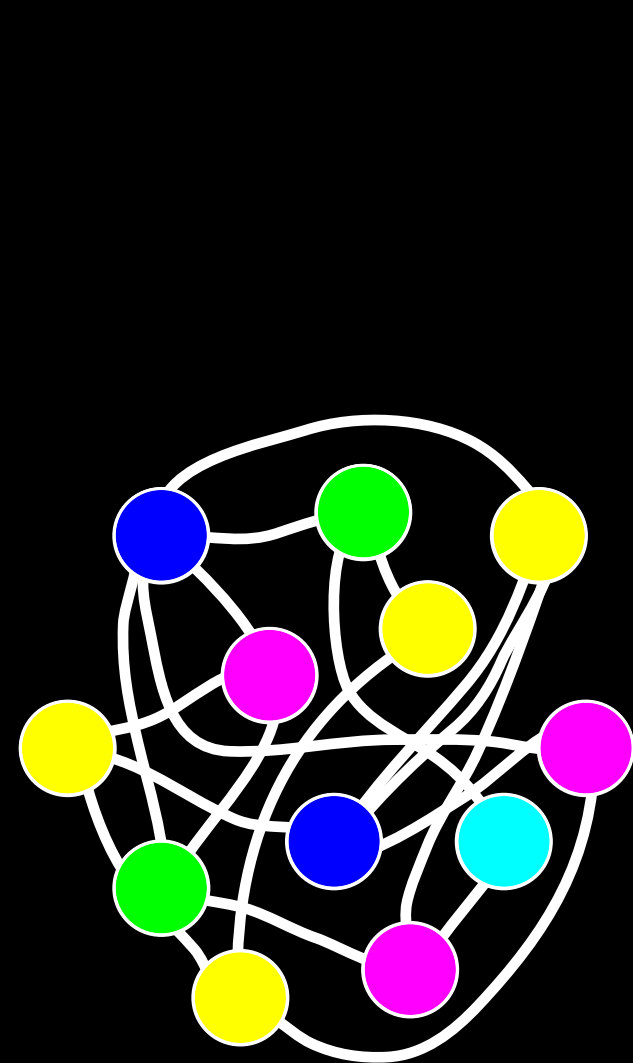
how they interact

Graphical model

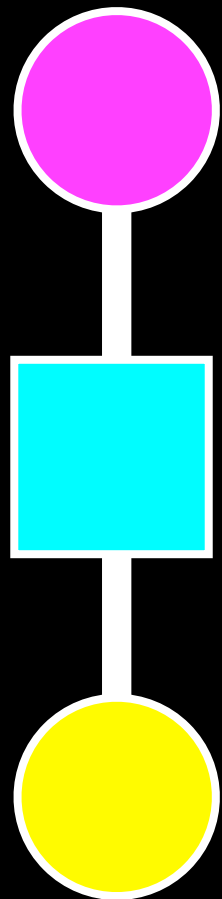
how the interactions are *used*

***Message-Passing
algorithm***

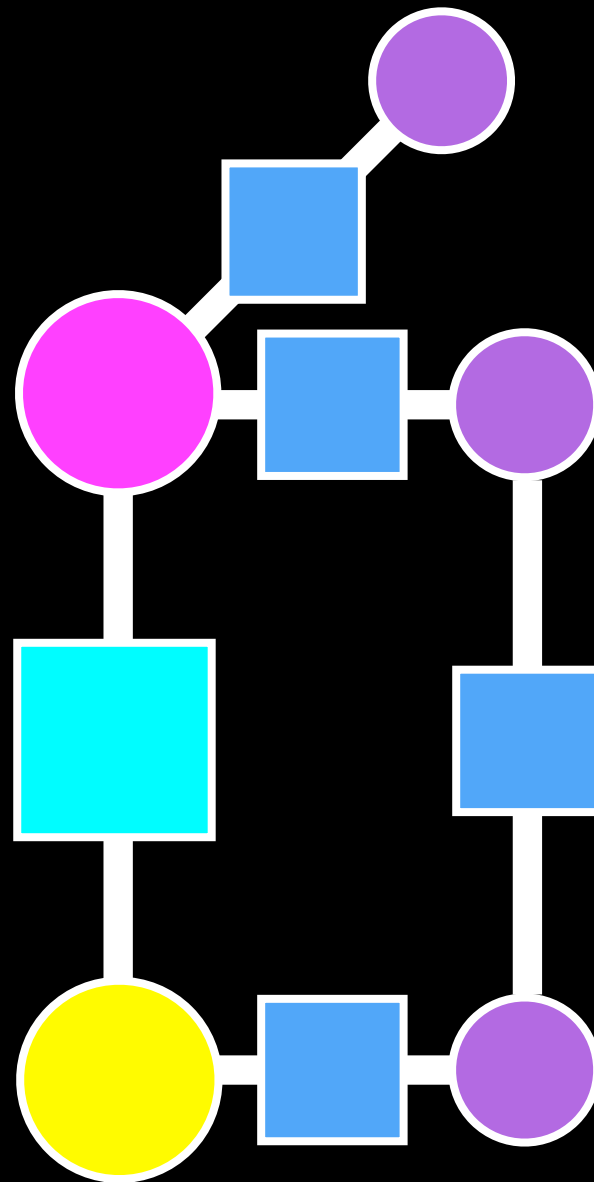
Applying message-passing to novel tasks



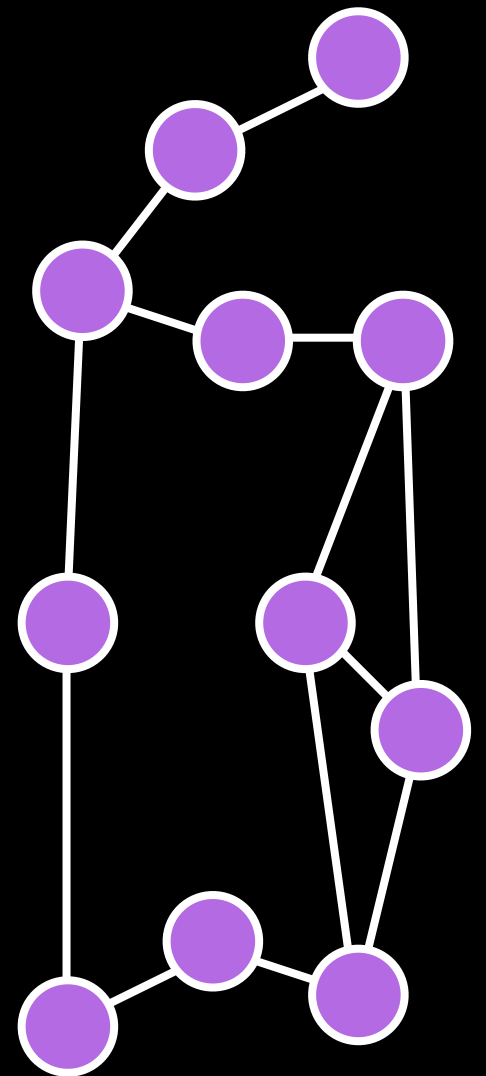
Brain
neural
network



Message
passing
nonlinearity



Apply to
new graphical
model structure



Relax to
novel neural
network
OR

**Next up:
applying methods
to real brains**

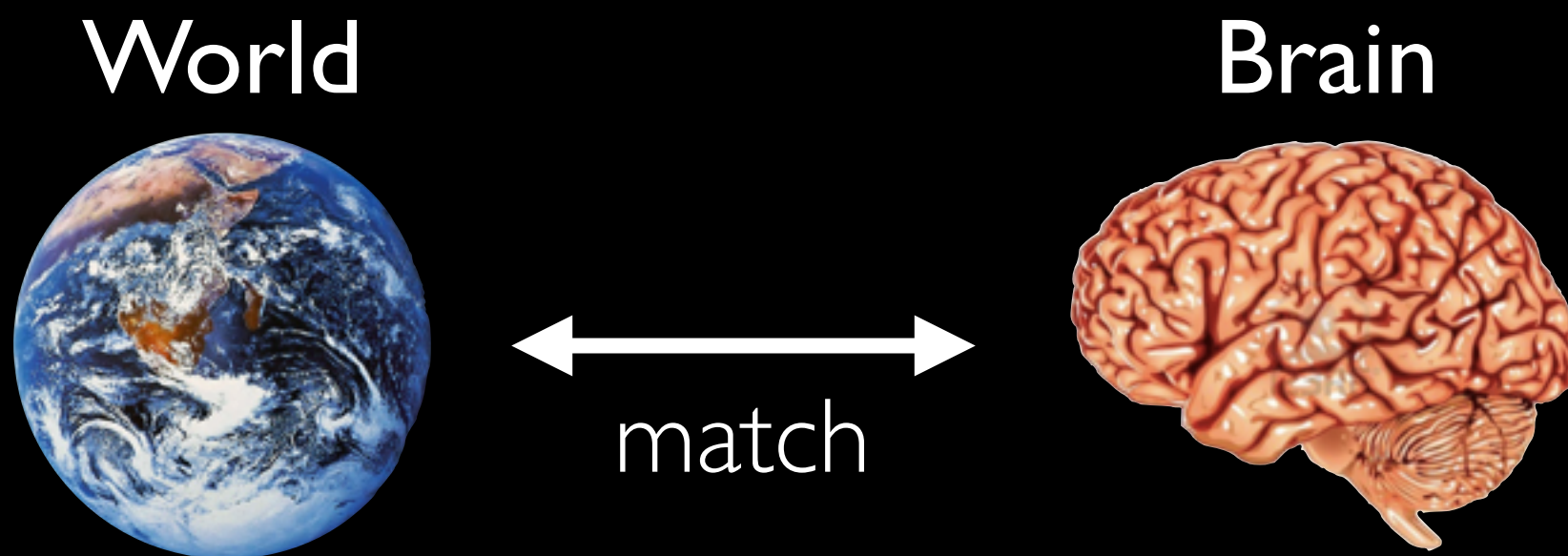
stimulus: orientation field

recordings: V1 responses*

*not to same stimulus
recordings from Tolias lab

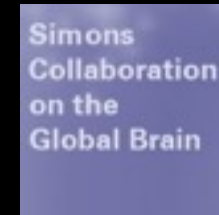
mementos:

- **Neurons can perform inference *implicitly* in a graphical model distributed across a population.**
- **New method to discover message-passing algorithms by modeling transformations of decoded task variables**



acknowledgements

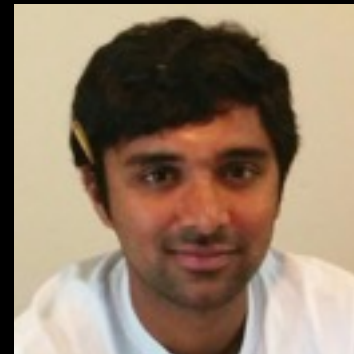
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